## **AuTO**: Scaling Deep Reinforcement Learning for Datacenter-Scale Automatic Traffic Optimization

Li Chen, Justinas Lingys, Kai Chen, Feng Liu

### **Datacenter Network**

- Network Flow
  - A sequence of packets from a destination to source
- Network Congestion
- Big Switch Assumption and Pitfalls

## **Traffic Optimization**

- Routing Optimizations
- Load balancing
- Scheduling Optimizations



#### **Important Ideas**

- Traffic optimizations (TO) require specialized knowledge
- TO based on heuristics
- Turn around time is denominated in weeks

## Key Problems when Implementing RL

- Using RL for flow calculation at runtime has high latency
- Calculating flow based on past results in poor performance
- High turn around time of traffic optimization

#### **Traditional RL Approach**

- Reinforcement learning for flow scheduling
- Leverages Priority queues
  - Flows with higher priorities get processed first

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- Deep reinforcement learning is unable to handle datacenter level traffic
  - Computation time > Flow life cycle



## **Expansion of Past Research**

- REINFORCE
  - Demonstrates policy iteration can converge to locally optimal policy
- Other TO systems
  - Only consider stochastic policies
  - State selected according to probability of distribution
- MLFQ (Multi-feedback queueing)
  - Divides process into multiple queues with independent priority



Figure 6: Comparison of deep stochastic and deep deterministic policies.

## AuTO

- Two level system
  - Peripheral (PS) and Central (CS)
- Peripheral system on end-hosts
  - Collects flow information
  - Executes local traffic optimizations
- Central System
  - Aggregates peripheral system actions
  - $\circ \quad \text{Network Described as } \{n_1, m_1, m \Box\}$



## **Peripheral System**

- Collects and tags flows
  - Tagged actions are influence from Central System
- Monitoring Module
- Enforcement Model
  - Receives actions from central system
  - Traffic Optimizations Decision



## **Central System**

- Uses two RL agents
  - srla & Irla
- sRLA
  - Deep Deterministic Policy Gradient
  - 700 features per-server
  - Outputs MLFQ threshold
- IRLA
  - Generates actions for long flows
  - Fully Connected
  - 10 hidden layers
  - 136 features per-server
  - Outputs probabilities of actions for active flows



## sRLA in Depth

- Inspired by staged (SEDA) event driven architecture design
- DDPG
  - Actors have two fully-connected hidden layers
  - Outputs optimizes thresholds for MLFQ
  - Critics are three hidden layers
- Leverages CDF of flow size distributions
- Optimal set of thresholds to minimize FCT (flow completion time)

Algorithm 1: DDPG Actor-Critic Update Step

- 1 Sample a random mini-batch of N transitions  $(s_i, a_i, r_i, s_{i+1})$  from buffer
- 2 Set  $y_i = r_i + \gamma Q'_{\theta^{Q'}}(s_{i+1}, \mu'_{\theta^{\mu'}}(s_{i+1}))$
- 3 Update critic by minimizing the loss:  $L = \frac{1}{N} \sum_{i=1}^{N} (y_i - Q_{\theta^Q}(s_i, a_i))^2$
- 4 Update the actor policy using the sampled policy gradient:

$$\nabla_{\theta^{\mu}} J \approx \frac{1}{N} \sum_{i=1}^{N} \nabla_{\theta^{\mu}}(s_i) \mu_{\theta^{Q}}(s_i) \nabla_{a_i} Q_{\theta^{Q}}(s_i, a_i) \Big|_{a_i = \mu_{\theta^{Q}}(s_i)}$$

5 Update the target networks:

$$\begin{aligned} \theta^{Q'} &\leftarrow \tau \theta^Q + (1 - \tau) \theta^{Q'} \\ \theta^{\mu'} &\leftarrow \tau \theta^\mu + (1 - \tau) \theta^{\mu'} \end{aligned}$$

where  $\gamma$  and  $\tau$  are small values for stable learning

#### Environment



Figure 7: Testbed topology.

## Evaluation

- How does AuTO compare to standard Heuristics?
- How does AuTO adapt?
- How fast can AuTO respond?
- What is the system overhead?

System is trained for 8 hours and then compared against generated heuristics

## **Traffic Distributions**

- Characteristics
  - $\circ$  flow size, distribution and load
- Homogeneous
- Spatially Heterogeneous
  - Cluster of for servers with fixed characteristics
- Spatially and Temporally Heterogeneous
  - Characteristics change periodically





Figure 8: Traffic distributions in evaluation.

#### Homogeneous Traffic



Average Flow Time Completion vs. Percentile

#### Spatially Heterogeneous Traffic



Average Flow Time Completion vs. Percentile

#### Temporally and Heterogenous Traffic



#### Impact of MLFQ Thresholds on FCT



Figure 14: Average FCT using MLFQ thresholds from sRLA vs. optimal thresholds.



Figure 15: p99 FCT using MLFQ Thresholds from sRLA vs. optimal thresholds.

#### Load Balancing



Figure 16: Load balancing using lRLA (PG algorithm): difference in number of long flows on links.

#### **Central Sysetm Latency**



Figure 18: CS response latency: Scaling short flows

Figure 17: CS response latency: Traces from 4 runs.

## Commentary

- Design can be described as over-complicated
  - Does not take into account current network advancements
  - System can leverage abstractions of software defined networking
- Scaling implications of an approach that relies on agents on every server

# Reinforcement Learning for Data center Congestion Control

Chen Tessler, Yuval Shpigelman, Gal Dalal, Amit Mandelbaum, Doron Haritan Kazakov, Benjamin Fuhrer, Gal Chechik, and Shie Mannor

## **Reinforcement Learning in Context**

- Congestion Control
  - Requires observibility
  - Multi-objective management
- Problem Structure
  - Multi-agent
  - Multi-objective
  - Partially observed

## Contributions

- PCC-RL
  - Capable of maintaining high switch utilization
- OMNeT++ Evaluation Suite
- Testing Agents
  - RL POMDP

#### Baseline

Ala	4	4 host	ts	$8 \mathbf{hosts}$					
Alg.	SU	FR	QL	SU	FR	QL			
PCC-RL	94	77	6	94	97	8			
DC2QCN	90	91	5	91	89	6			
HPCC	71	18	3	69	60	3			
SWIFT	76	100	11	76	98	13			

Alg.	128 to 1			1024 to 1			4096 to 1			8192 to 1						
	SU	FR	QL	DR	SU	FR	QL	DR	SU	FR	QL	DR	SU	FR	QL	DR
PCC-RL	92	95	8	0	90	70	15	0	91	44	26	0	92	29	42	0
DC2QCN	96	84	8	0	88	82	17	0	85	67	110	0.2	100	72	157	1.3
HPCC	83	96	5	0	59	48	27	0	73	13	79	0.2	86	8	125	0.9
SWIFT	98	99	40	0	91	98	66	0	90	56	120	0.1	92	50	123	0.2

#### Findings

